

# LISTER PNEUMATIC EXCAVATION AT MARE CRISIUM

PRELIMINARY DRILLING REPORT FROM BLUE GHOST

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HONEYBEE ROBOTICS, A BLUE ORIGIN COMPANY

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# LSITP Objectives and LISTER Approach

**LISTER's goal is to characterize heat flow from the interior of the Moon** in support of the following:

*Science Mission Directorate (SMD)*

Better understand thermal evolution and differentiation history of the Moon

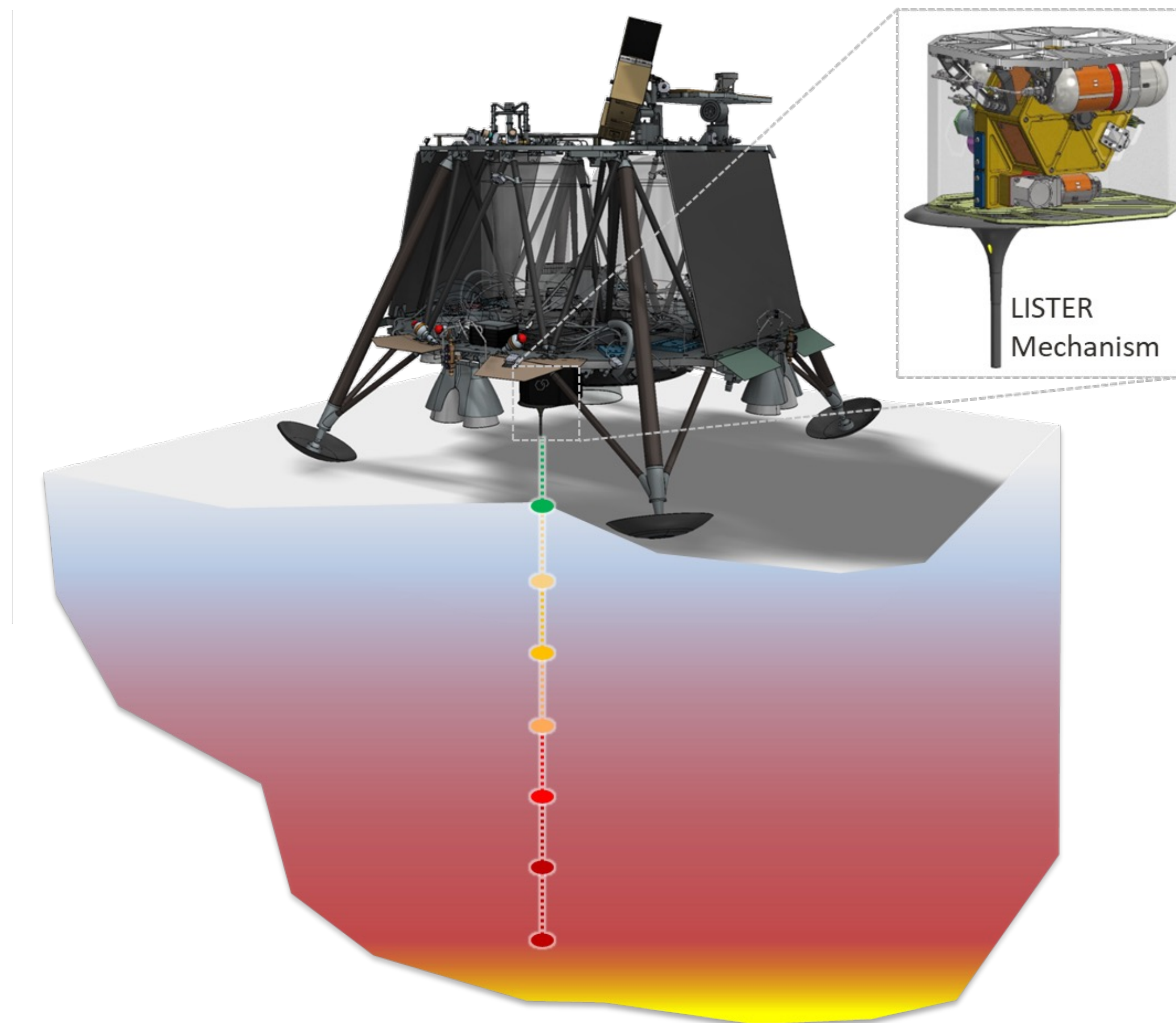
*Human Exploration and Operations Mission Directorate (HEOMD) Strategic Knowledge Gaps (SKGs)*

Understand lunar resource potential and how to work and live on the lunar surface

*Space Technology Mission Directorate (STMD)*

Enhance capabilities for future science and exploration missions and commercial Moon development

In support of these goals, **LISTER's objective is to measure the thermal gradient and conductivity of the lunar subsurface penetrated by its drilling probe tip.**





# LISTER as Drilling Tech Demonstration



LISTER's low-mass and low-volume drilling system can **drill holes** and **produce regolith samples** from known depths for science, exploration, and commercial missions.



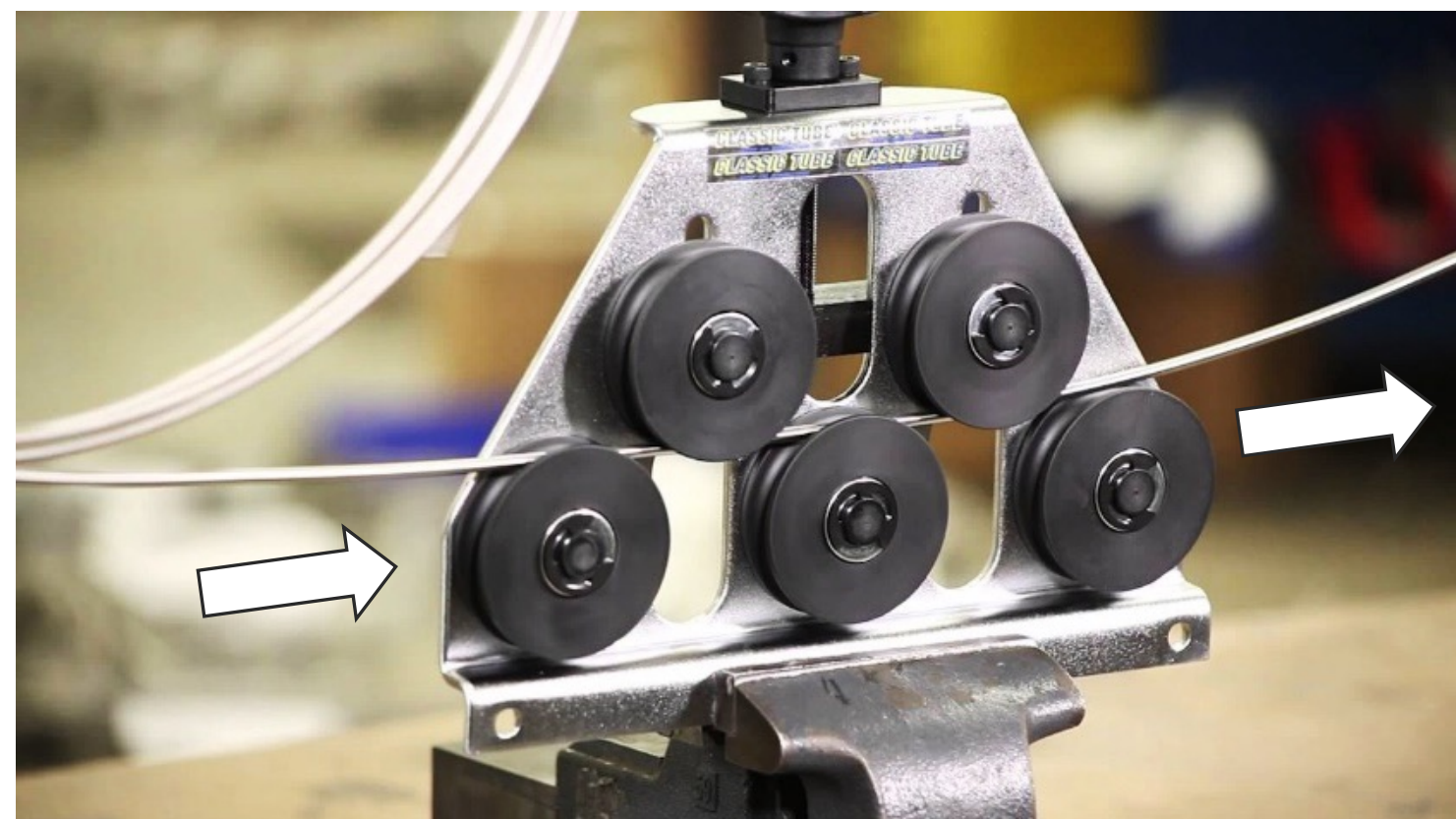
# Deployment Subsystem Overview

Based on COTS and industrial roller straightener designs

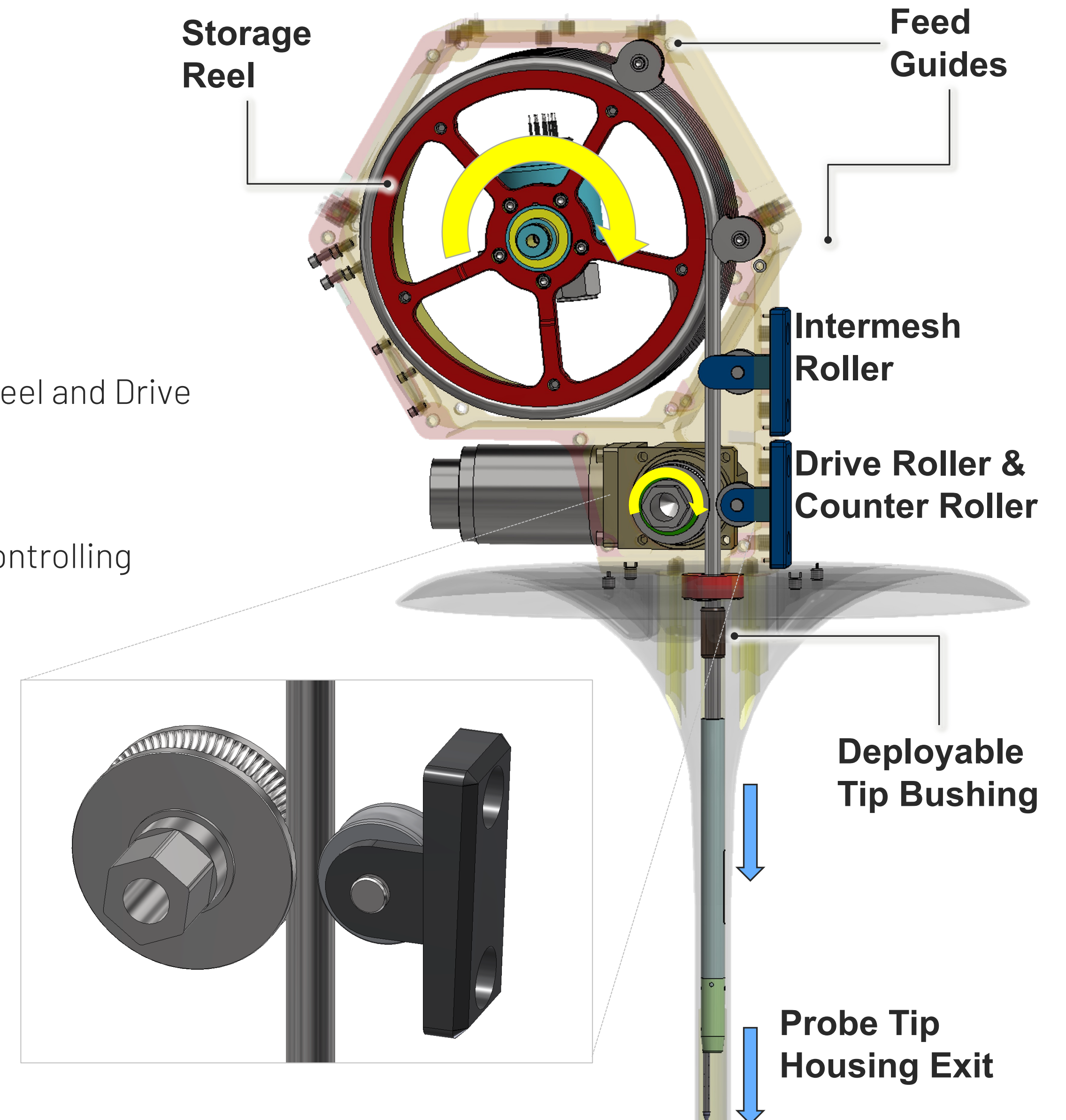
Coiled tubing is plastically yielded to deploy in straight form

1. Coiled Tubing is stored on **Storage Reel**
2. Drive Roller and Drive Counter Roller engage Coiled Tubing
3. Actuator rotates Drive Roller to pull Coiled Tubing
4. Intermesh (Straightener) Roller forms 3-roller straightener with Storage Reel and Drive Roller to straighten tubing
5. Feed Guides align Coiled Tubing to fixed deployment plane
6. Deployable Tip Bushing provides necessary final boundary condition for controlling straightness

COTS Tubing  
Straightener



**BLUE ORIGIN**





# Pneumatics Subsystem Overview

- HIGH-TRL COTS COMPONENTS AND CUSTOM MANIFOLD; ETU BUILT AND TESTED
- STORES N<sub>2</sub> GAS AT 5000 PSIA MEOP DESIGN PRESSURE
- DELIVERS GAS THROUGH STORAGE REEL GAS SWIVEL AND SPINDLE INTERFACE TO COILED TUBING

## Gas Supply Tanks

GN<sub>2</sub> 5000 psi

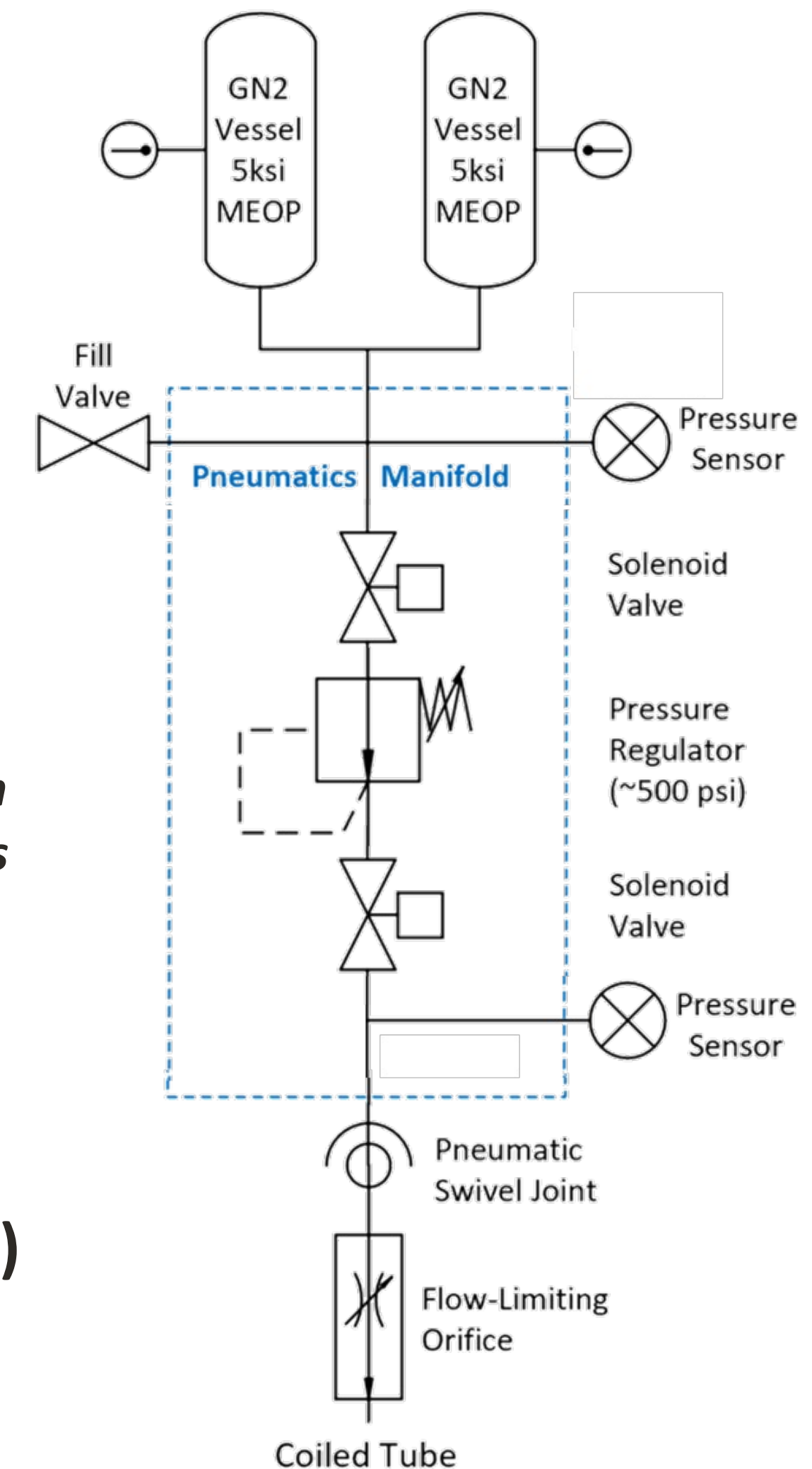
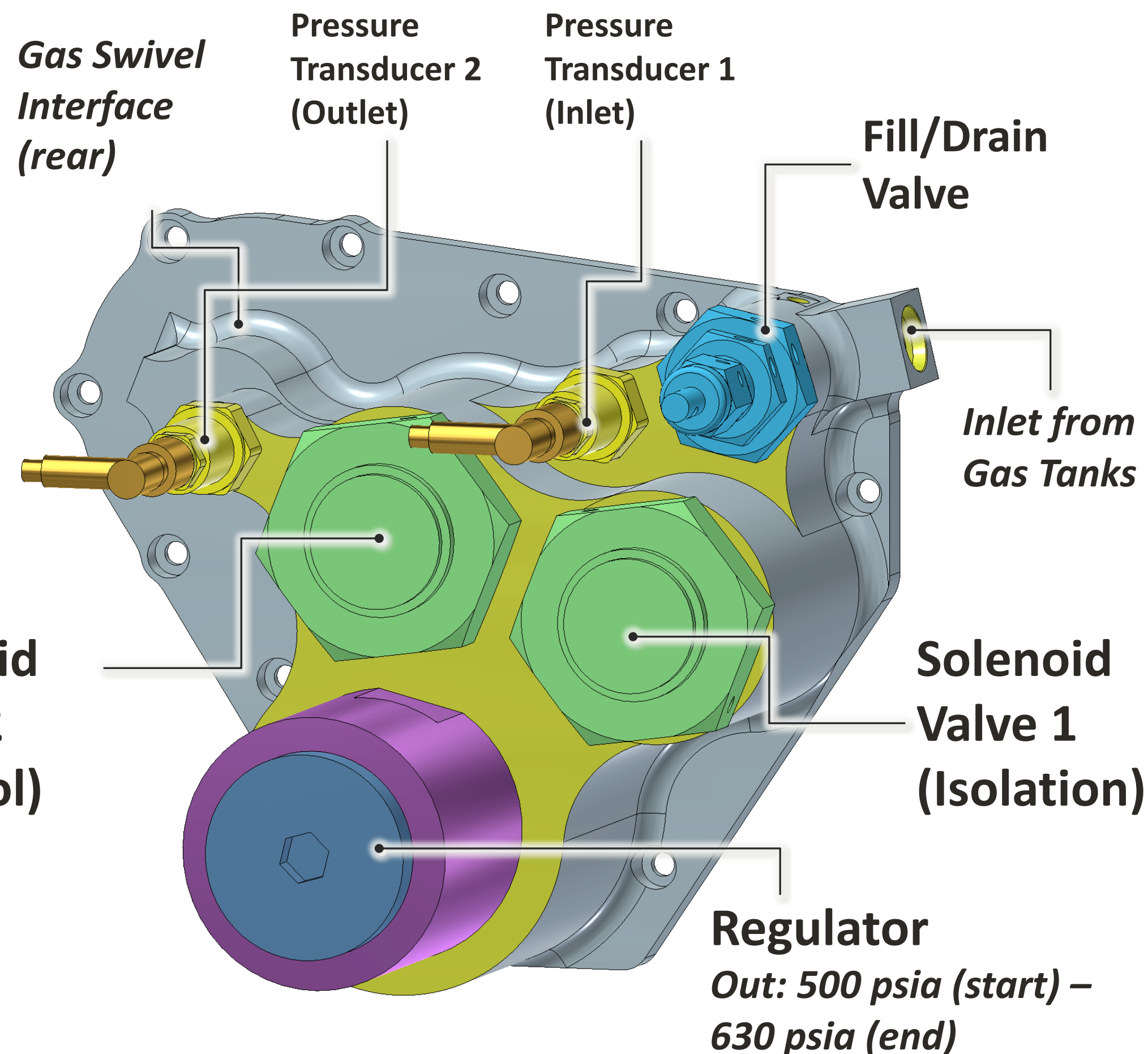
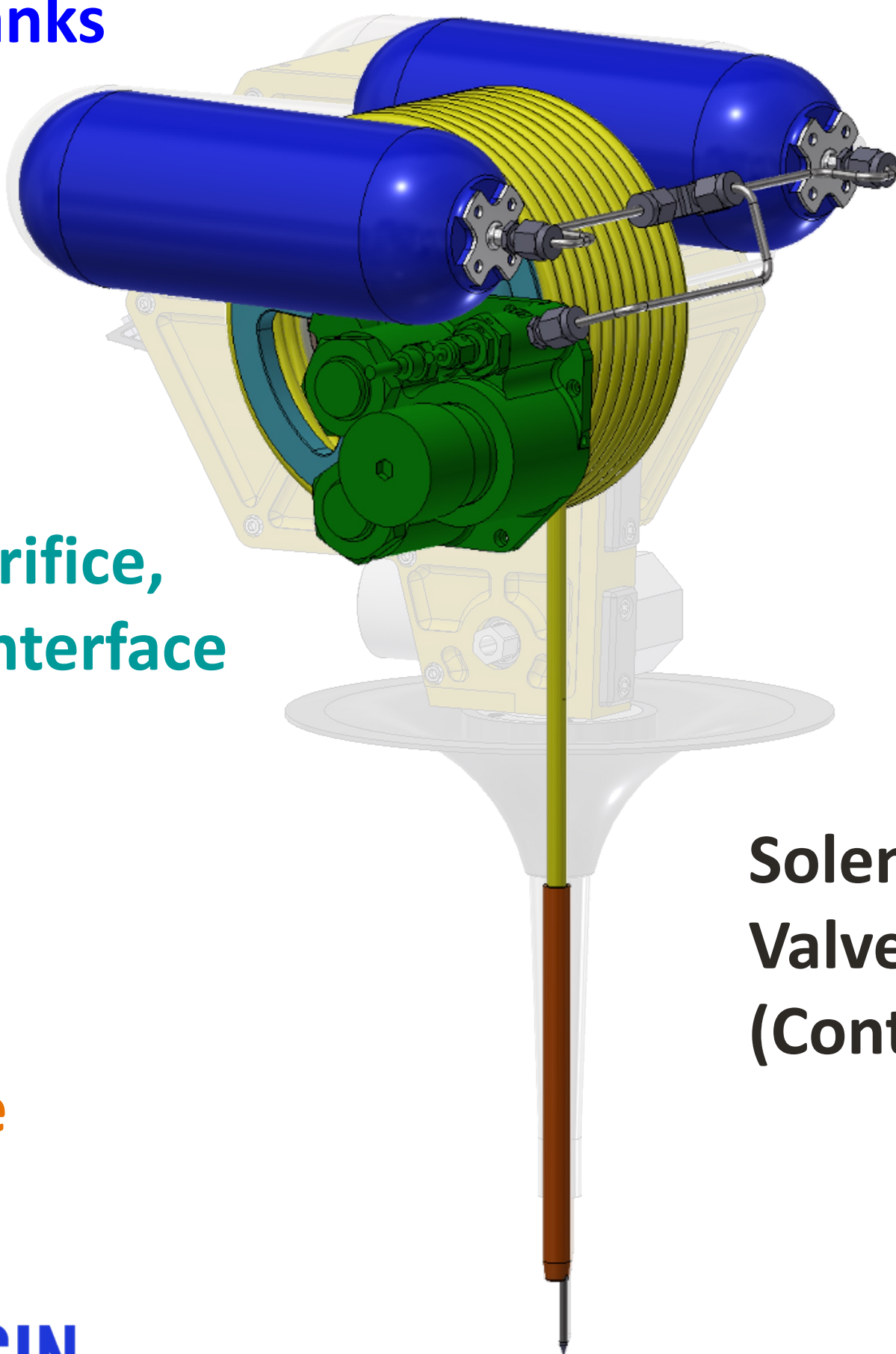
## Pneumatics Manifold

## Gas Swivel, Orifice, and Spindle Interface

## Coiled Tubing

## Spacer Nozzle

**BLUE ORIGIN**

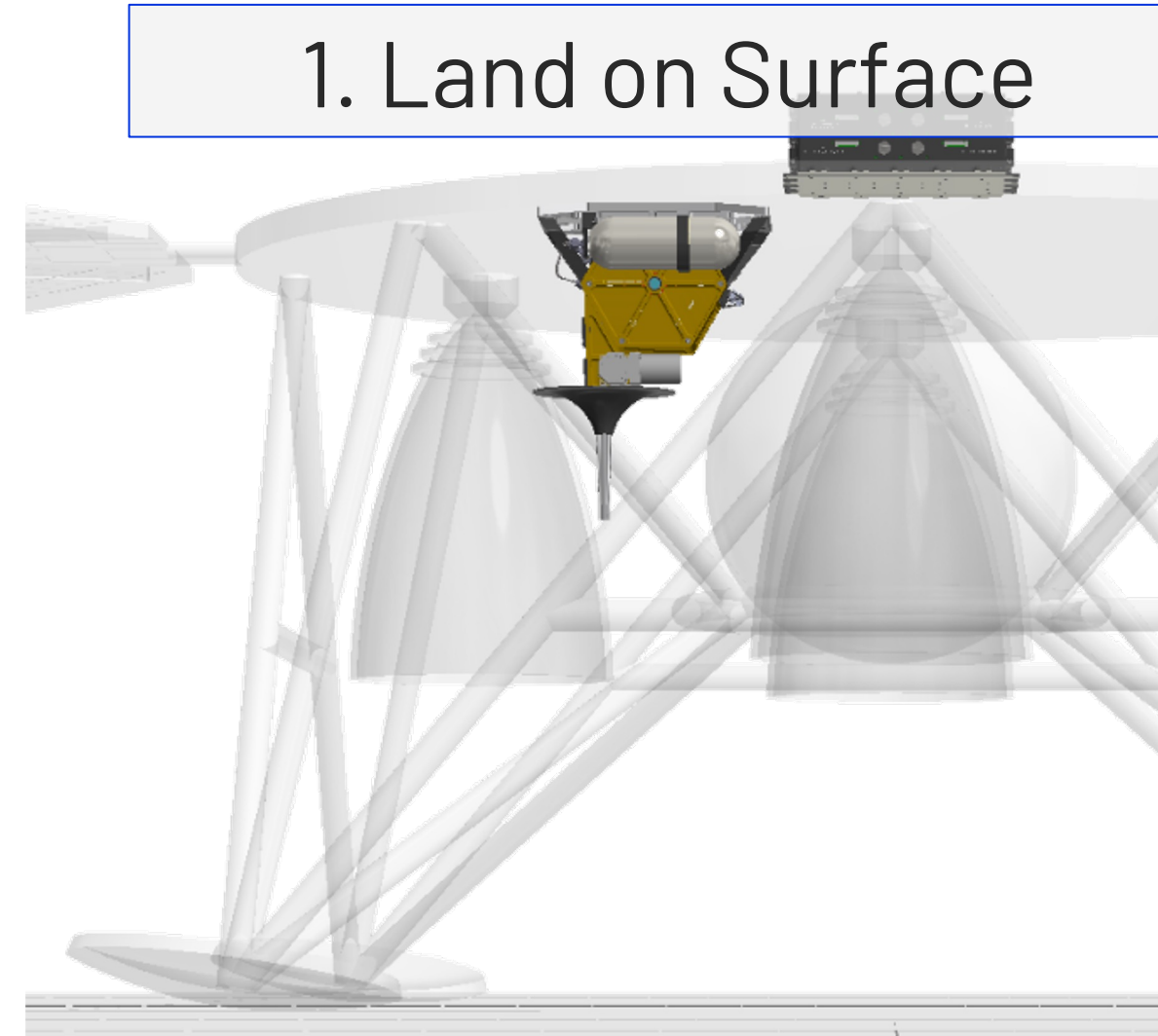




# LISTER Con-Ops

- LISTER is a Semi-Autonomous drilling system
  - Earth command sets target depth as well as safeties for early exits of the operation prior to reaching target depth
- Data is received on Earth and processed to decide how to approach the next bite
- LISTER seeks surface, buries the spacer nozzle to take first subsurface measurement, and then moves in commanded bites of up to 500mm

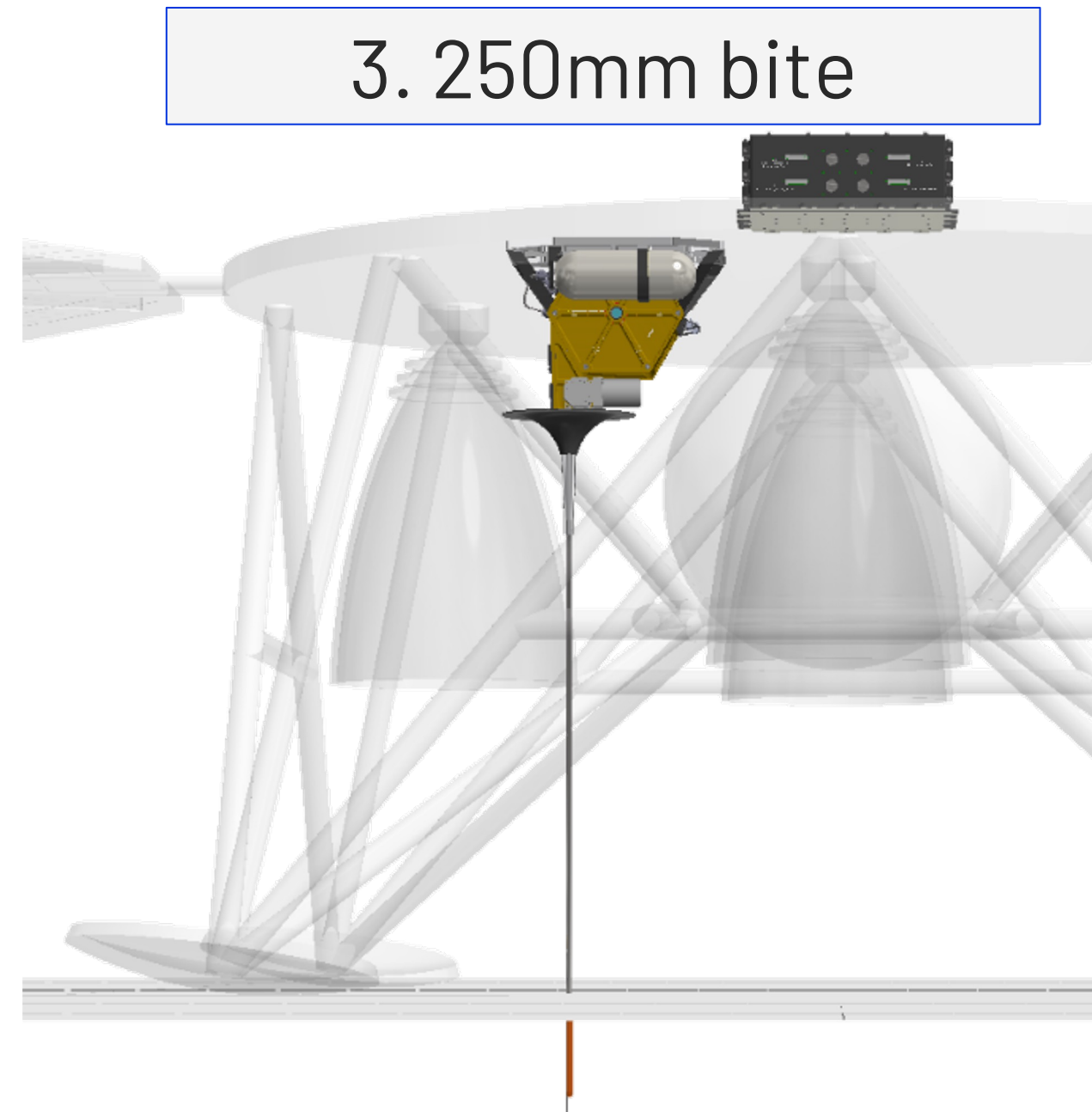
1. Land on Surface



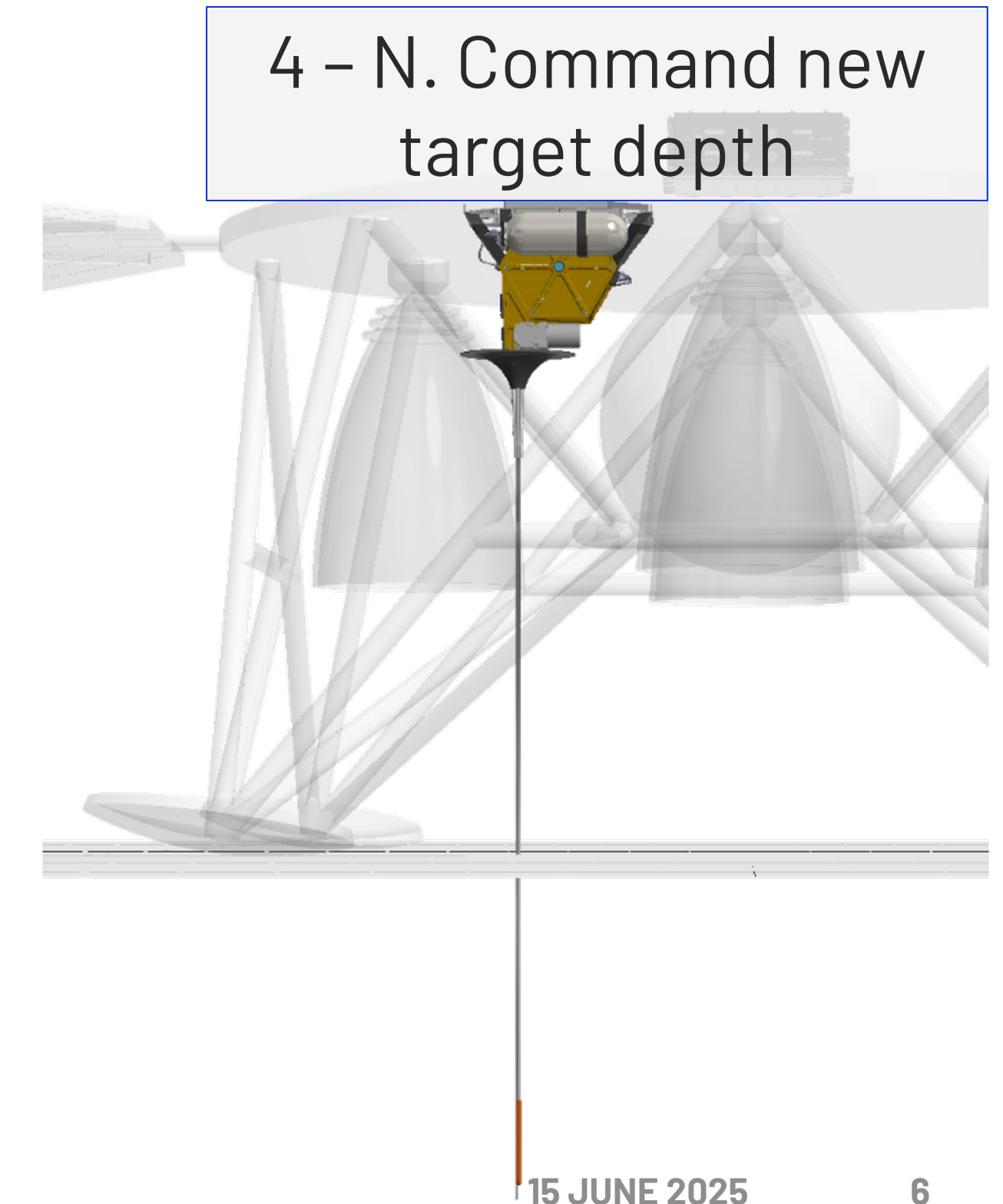
2. Drill Seeks Surface



3. 250mm bite



4 - N. Command new target depth

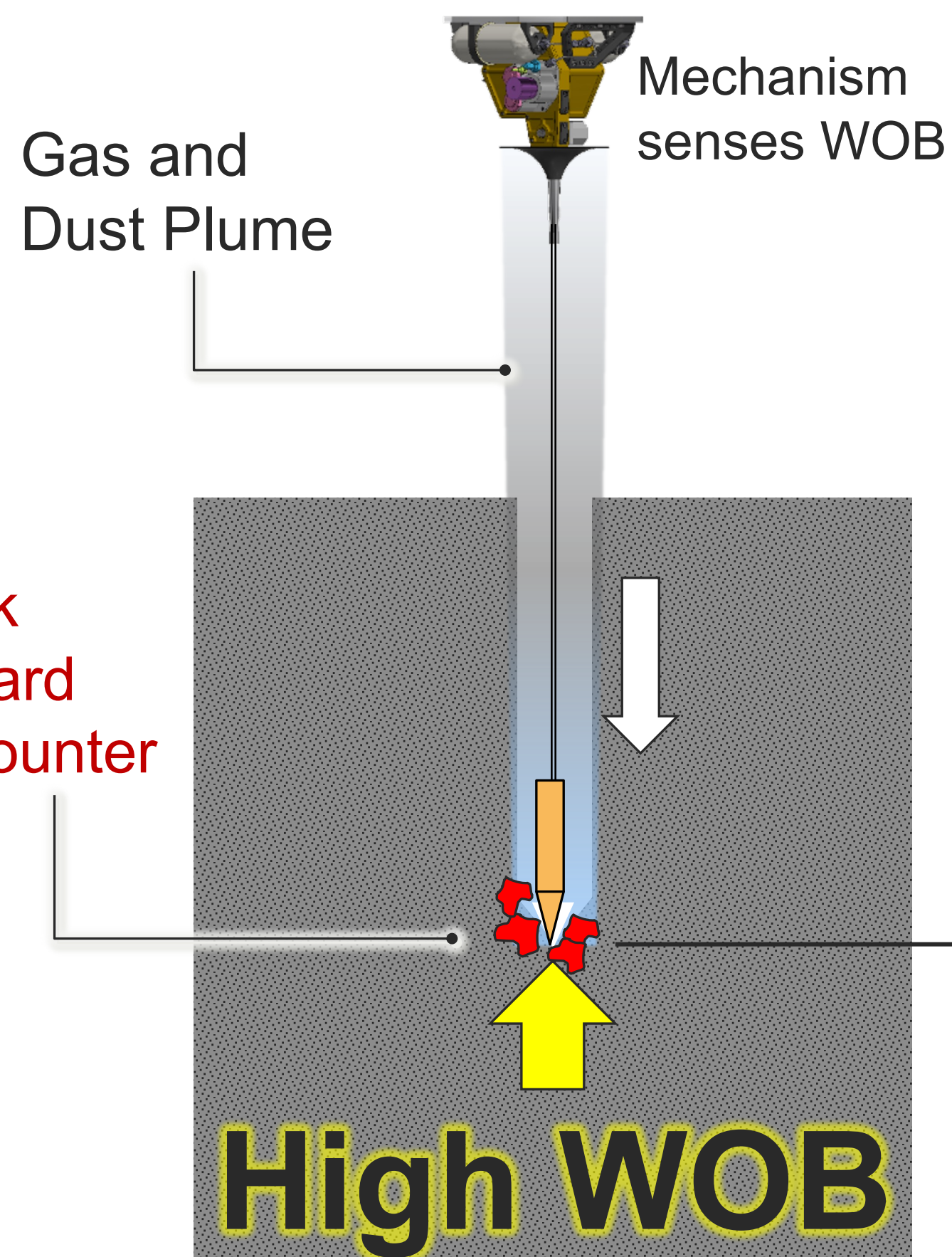




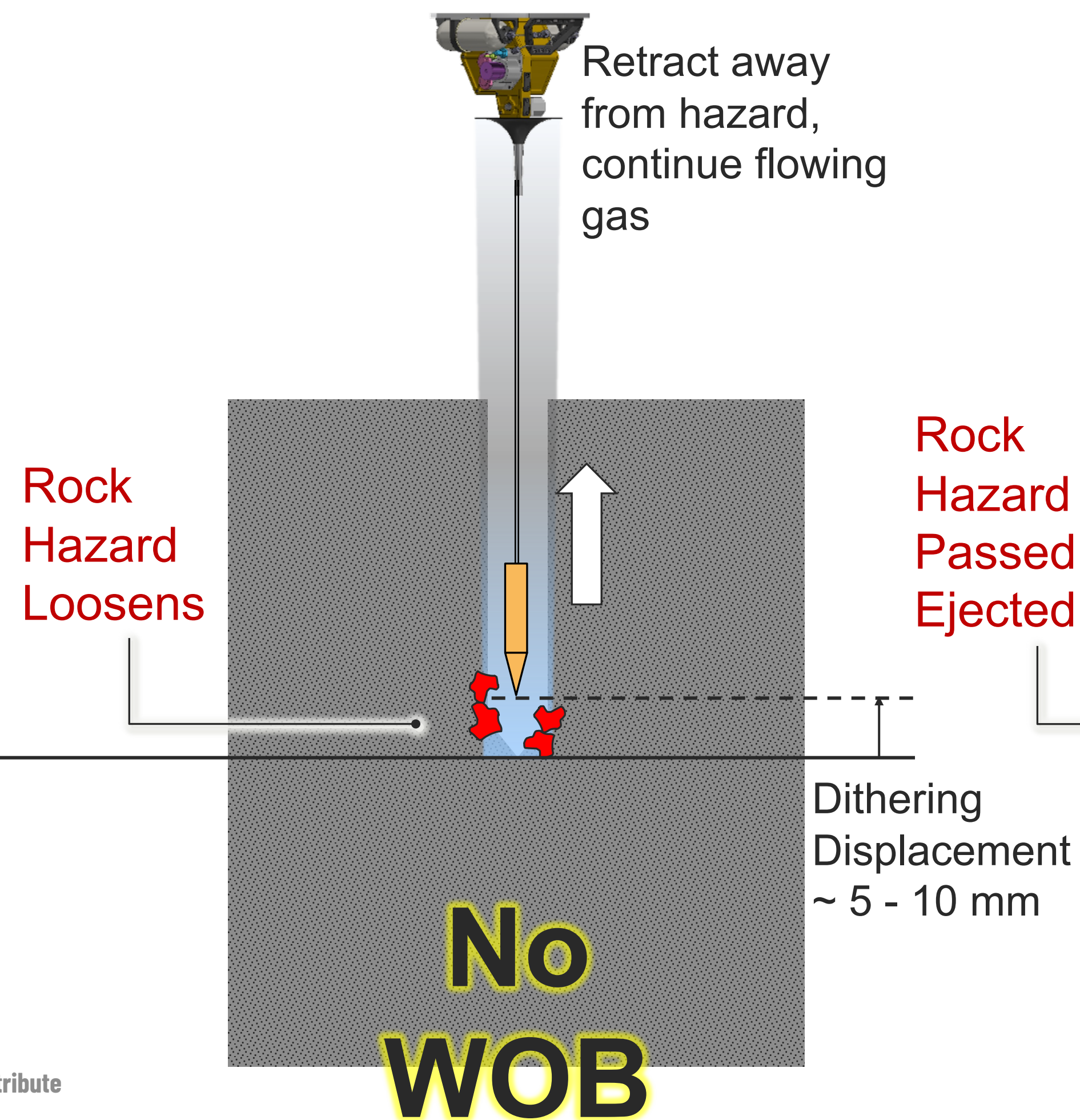
# Rock Hazard Mitigation using "Dithering"

**Dithering has proven effective against bridging and buildup of rocks in the borehole bottom**

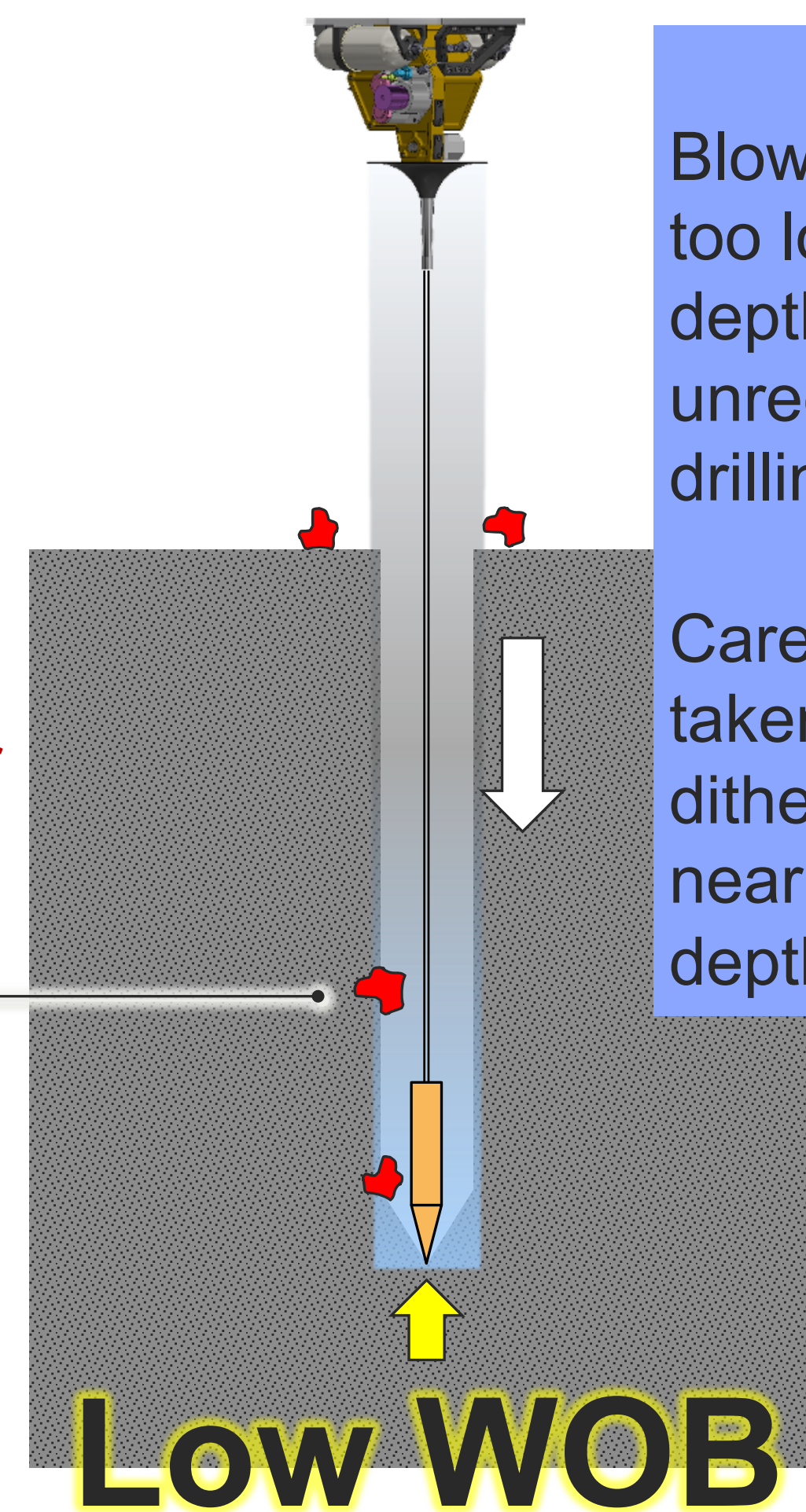
## 1 Dithering Trigger



## 2 Dithering Retraction away from Hazard



## 3 Resume Nominal Drilling after passing Hazard

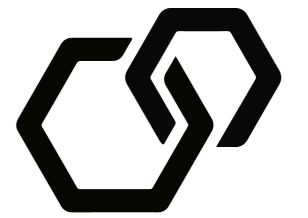


**Caution**  
Blowing gas for too long at one depth can lead to unrecoverable drilling failures

Care will be taken to limit dithering cycles near the same depth



# Project Background – Landing Site Selection

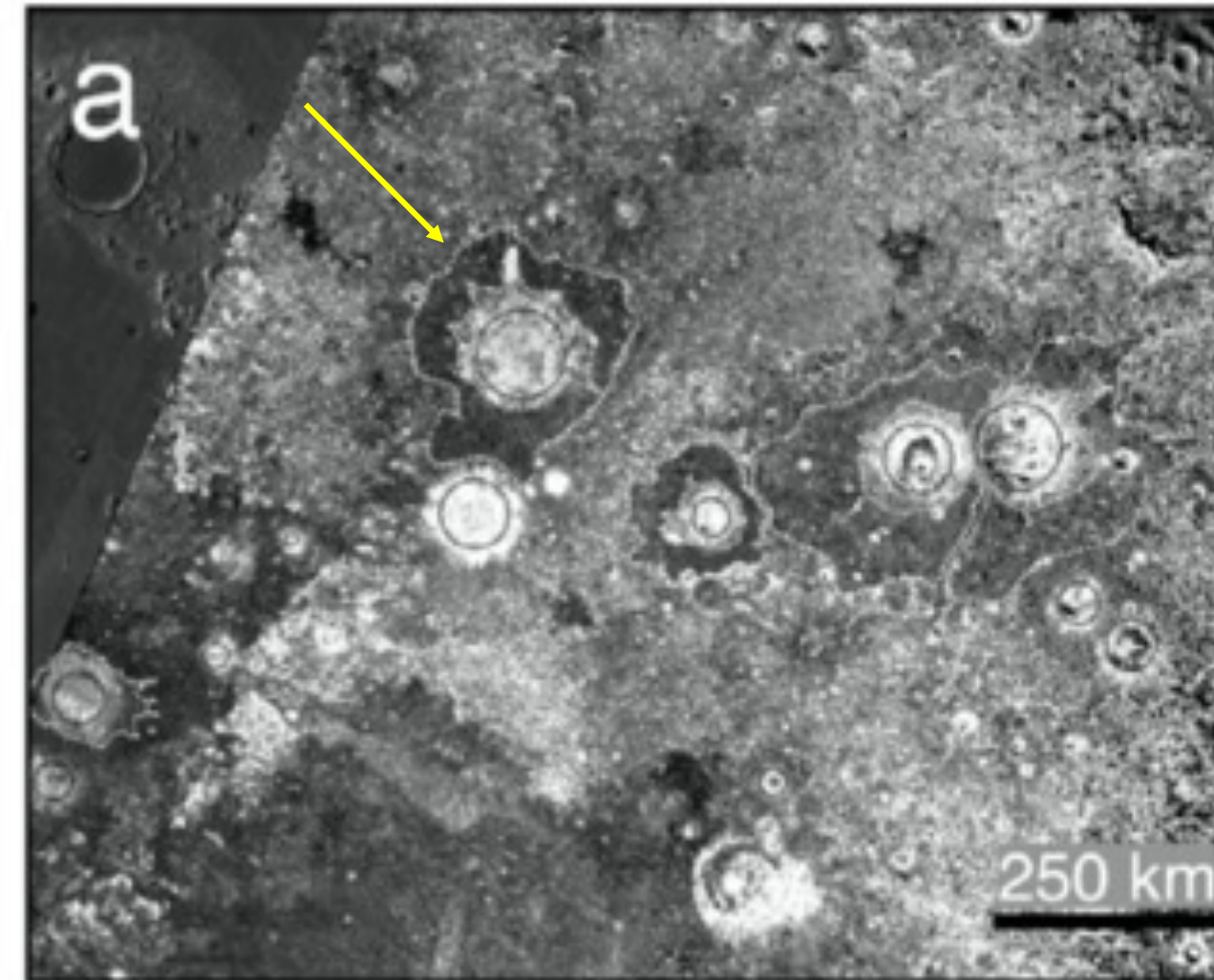


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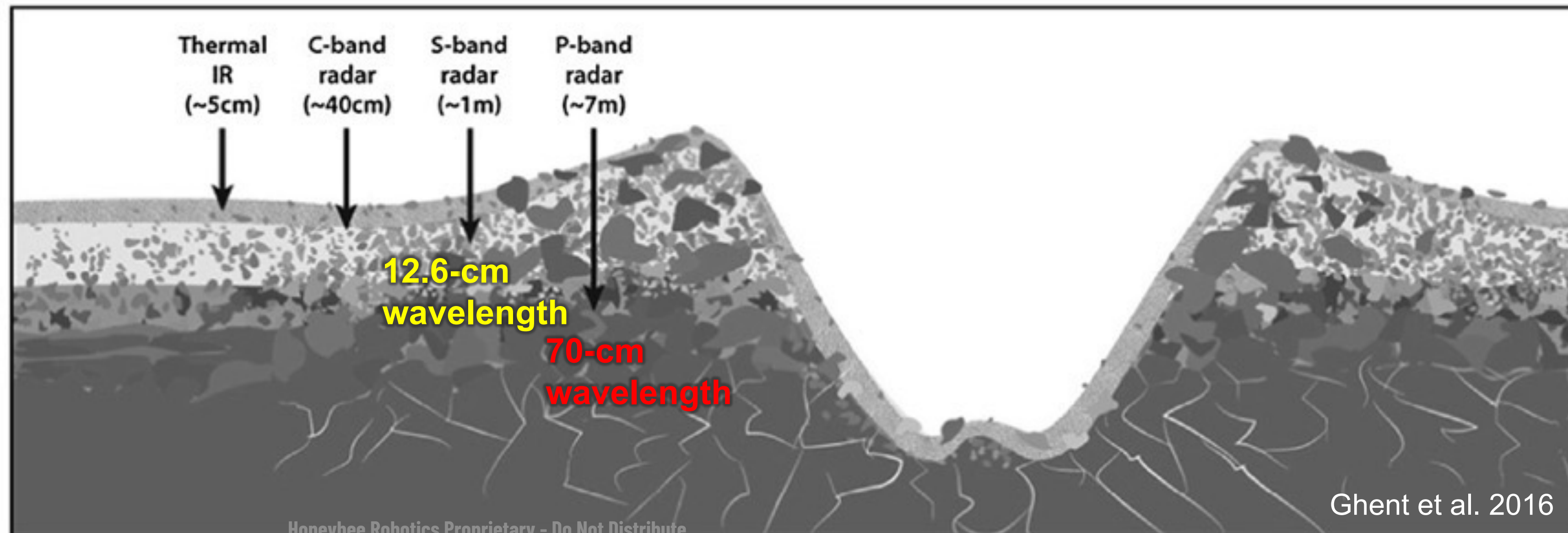
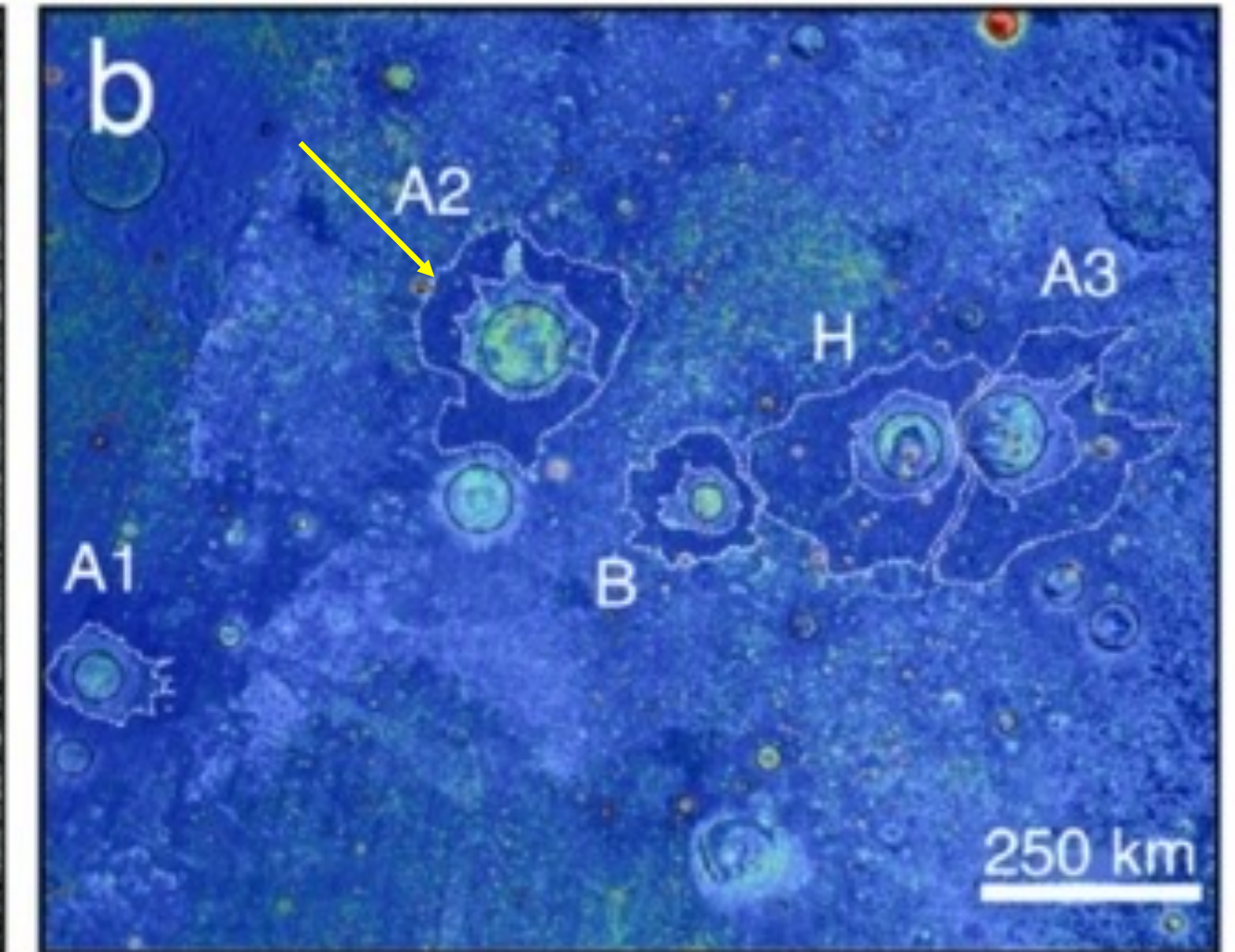
**Rock Abundance analysis:**  
LRO-Diviner and Arecibo  
Radar data were used to  
identify areas of low rock  
concentration from the surface  
down to ~7-m depth

Examples:

Arecibo P-band CPR



LRO-Diviner Rock Abundance





# LISTER Ops – First Operation



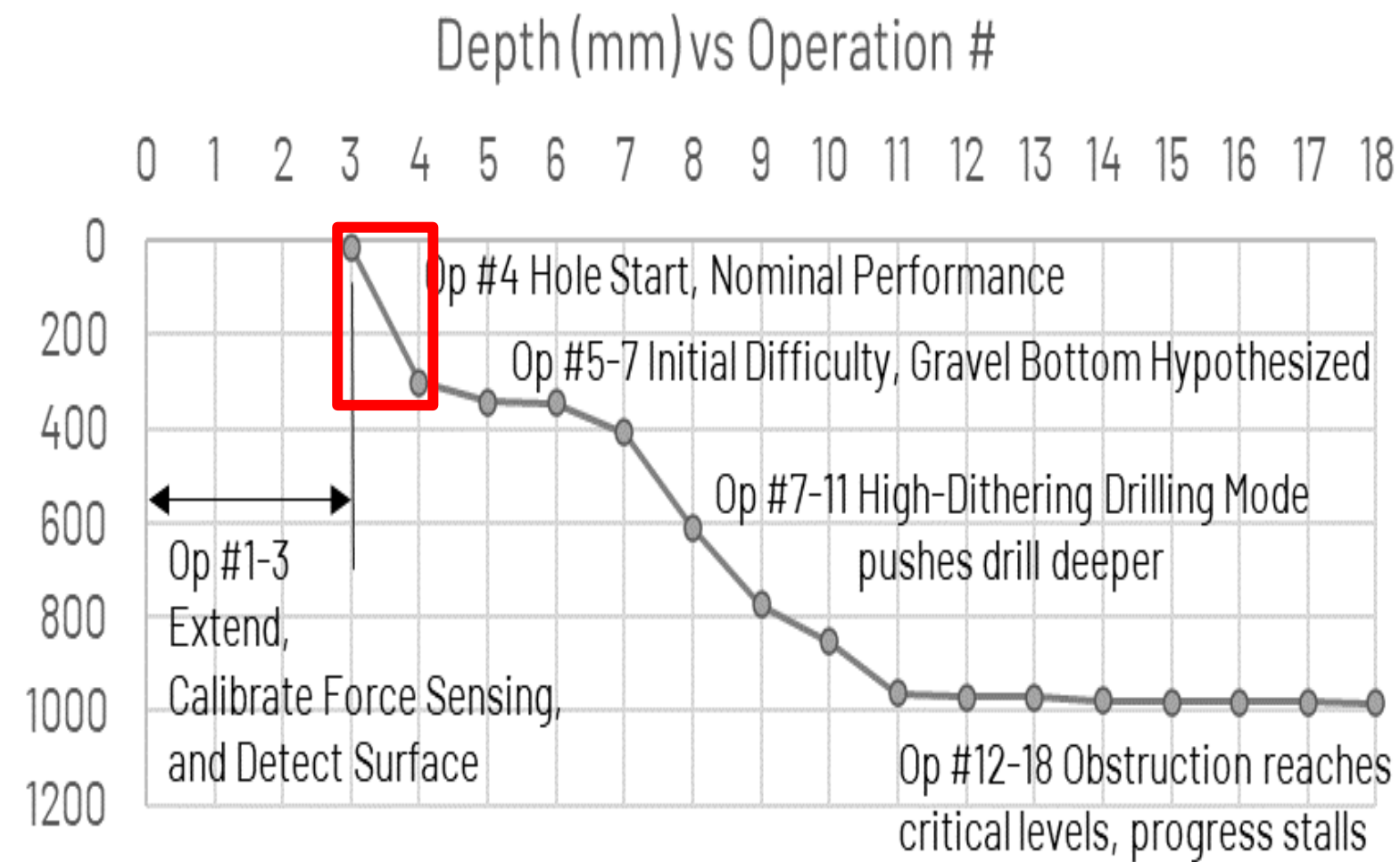
## BLUE GHOST MISSION 1

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NASA's Lunar Instrumentation for Subsurface  
Thermal Exploration with Rapidity  
Surface Operations



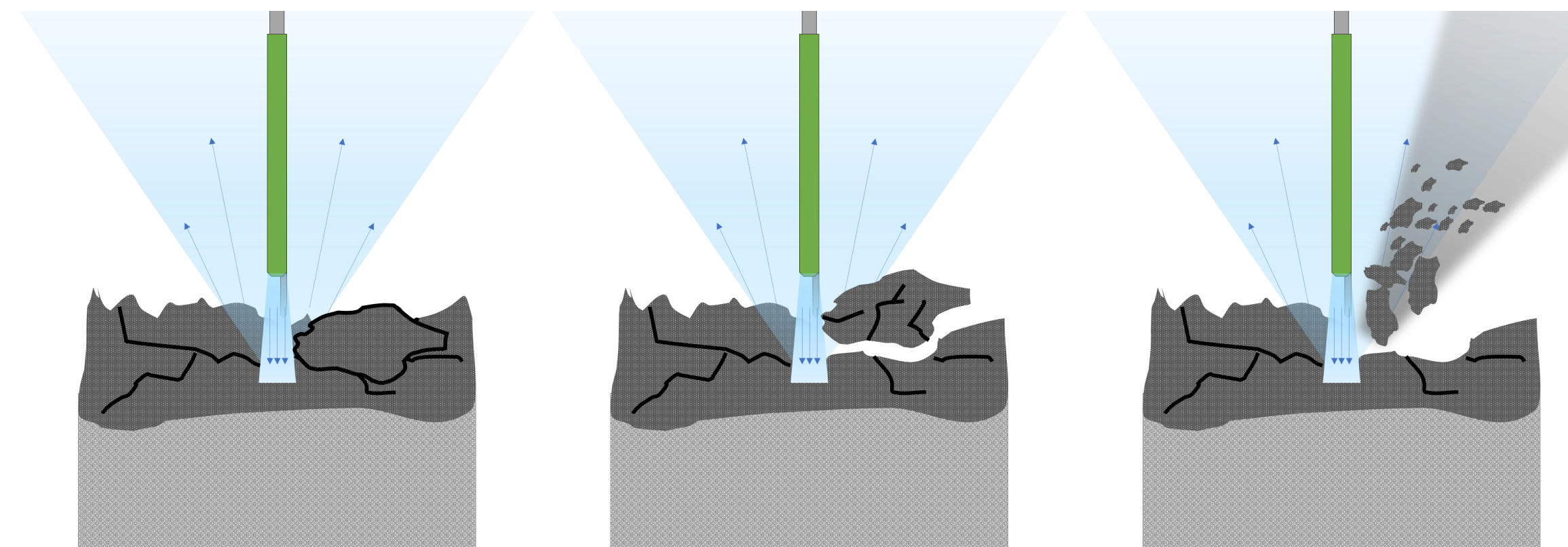
# Drilling at the Near Surface



## Hypothesized Rapid Ablation Cascade

Photo Courtesy Firefly Aerospace

- Highly compacted regolith at surface or in layers fractures into “eruption” of clumps of regolith
- Target depth of 250mm achieved, nominal performance



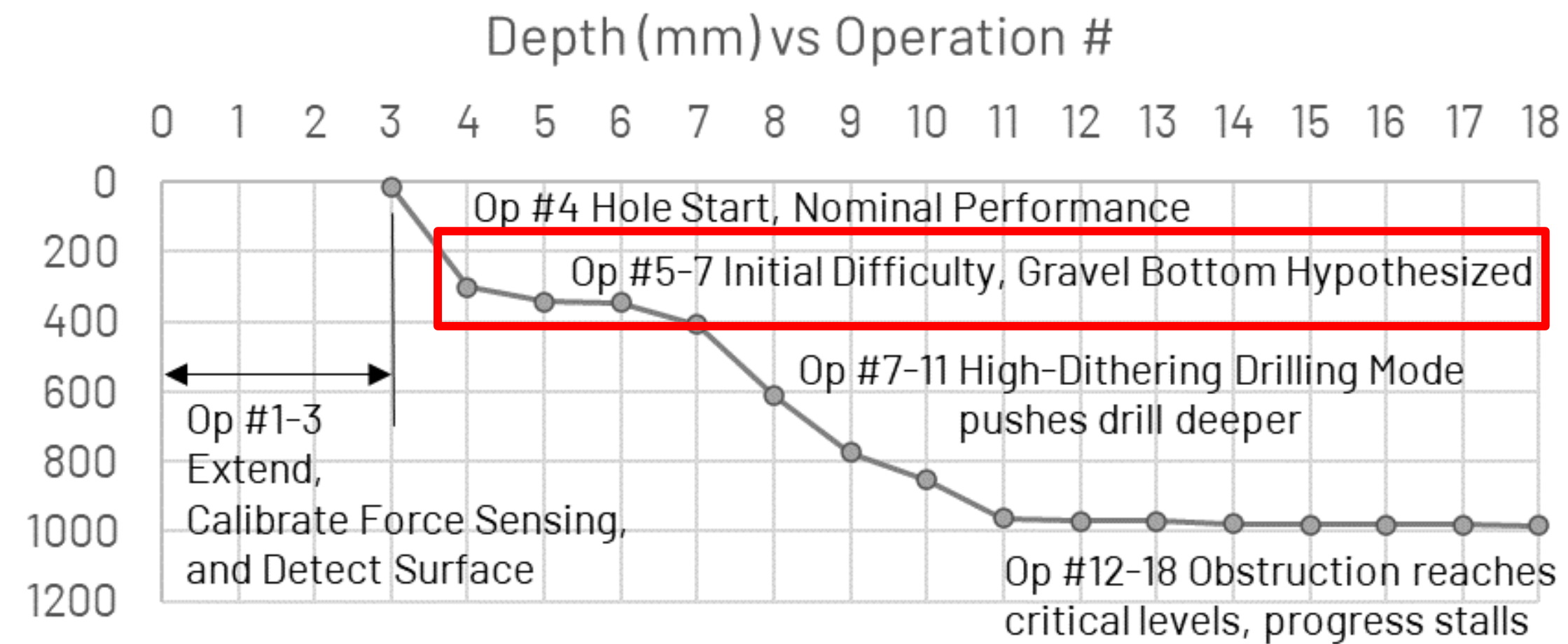
1 - Initial “fractures” develop as gas jet pressure disrupts consolidated crust

2 - Consolidated regolith clod separates and becomes lofted, developing new fractures

3 - New fractures cascade and clod rapidly disintegrates, leading to explosive ablation “eruption”



# First Obstacles



- As seen in developmental testing, when there is a layer or high concentration of “gravel” (>1mm sized pebbles), a “gravel bottom” condition can form
- Fines are excavated but gravel is not, leaving a bulb in the bottom hole

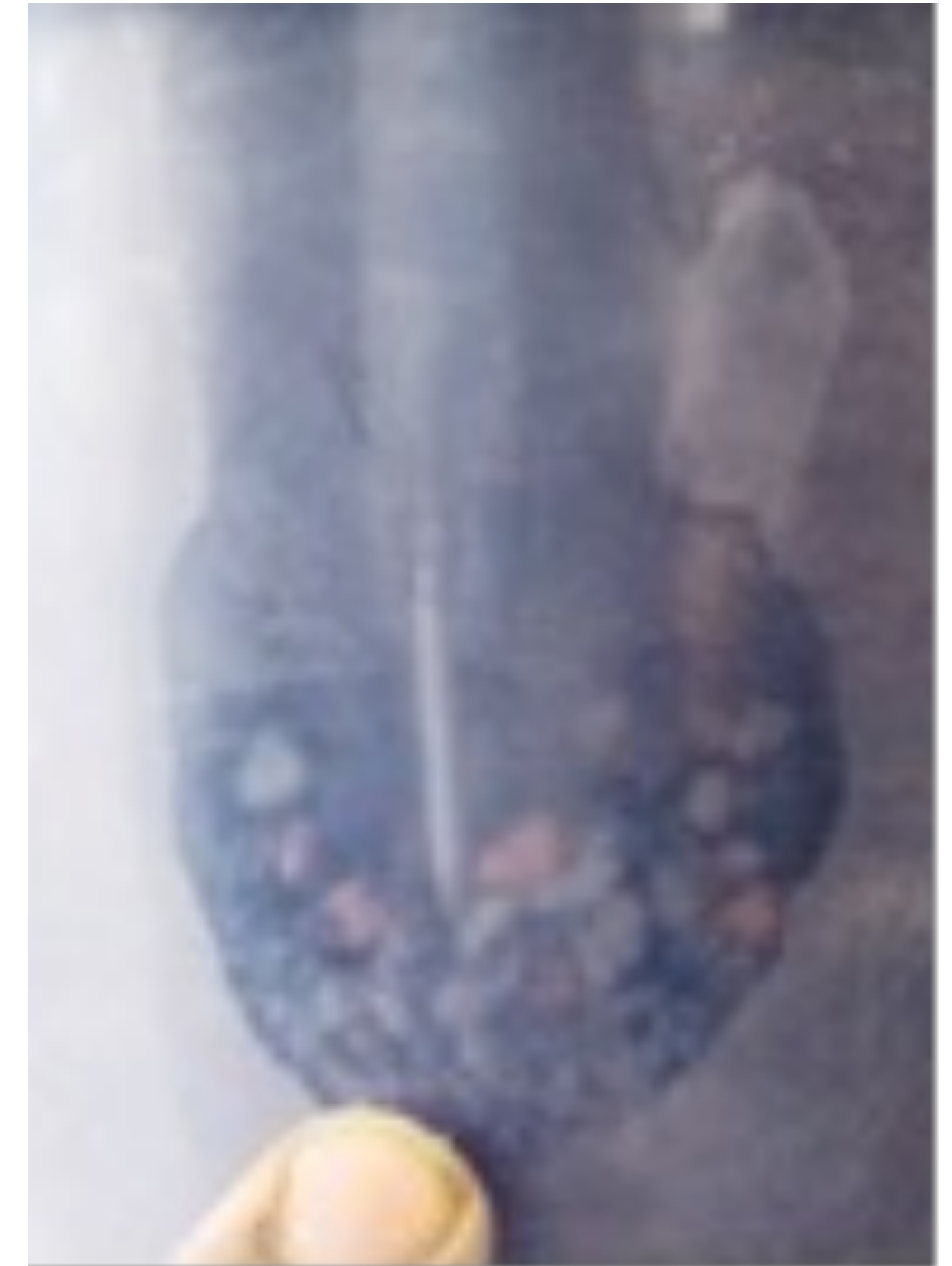
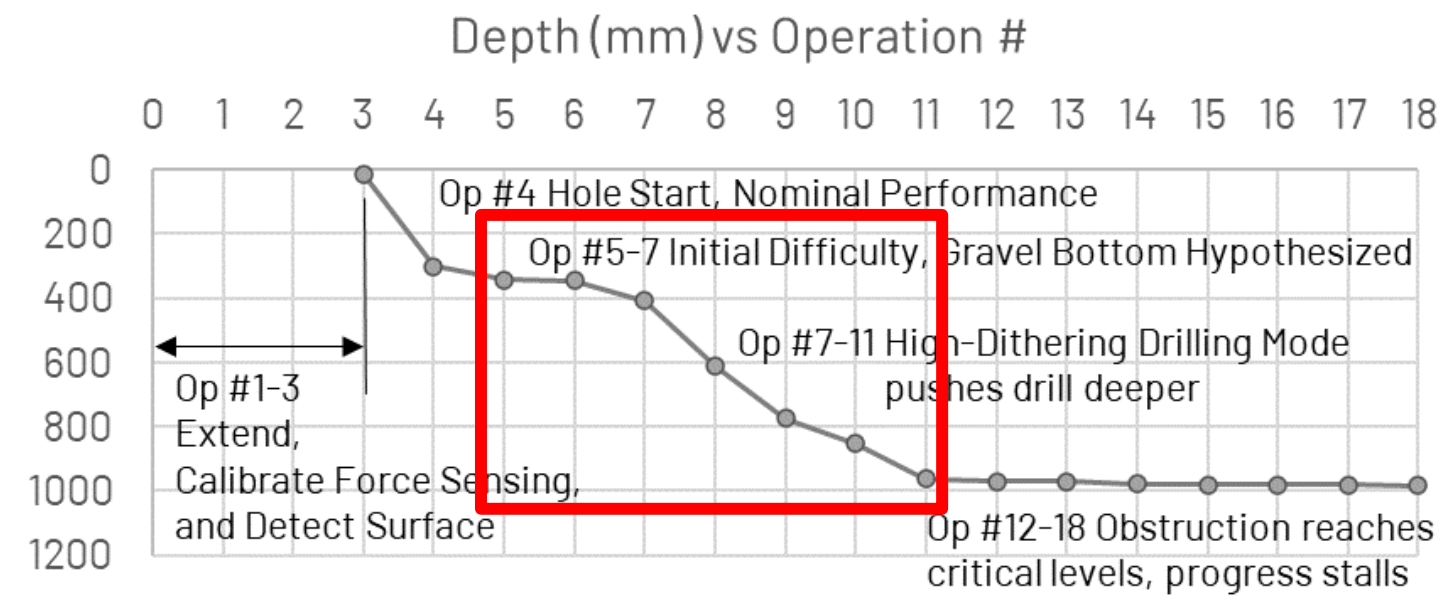


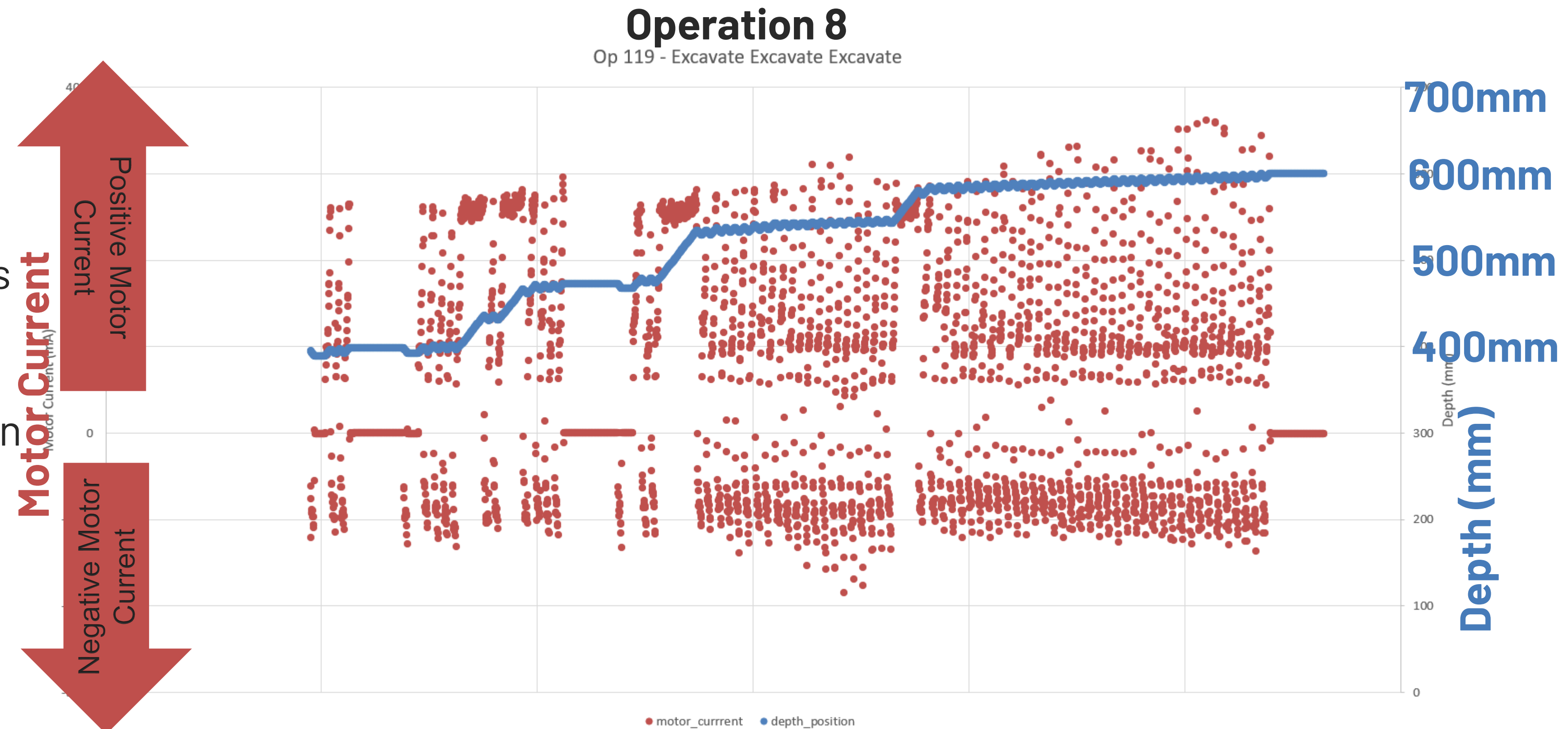
Photo from LISTER Developmental Testing



# Progress Through Changed Operational Parameters

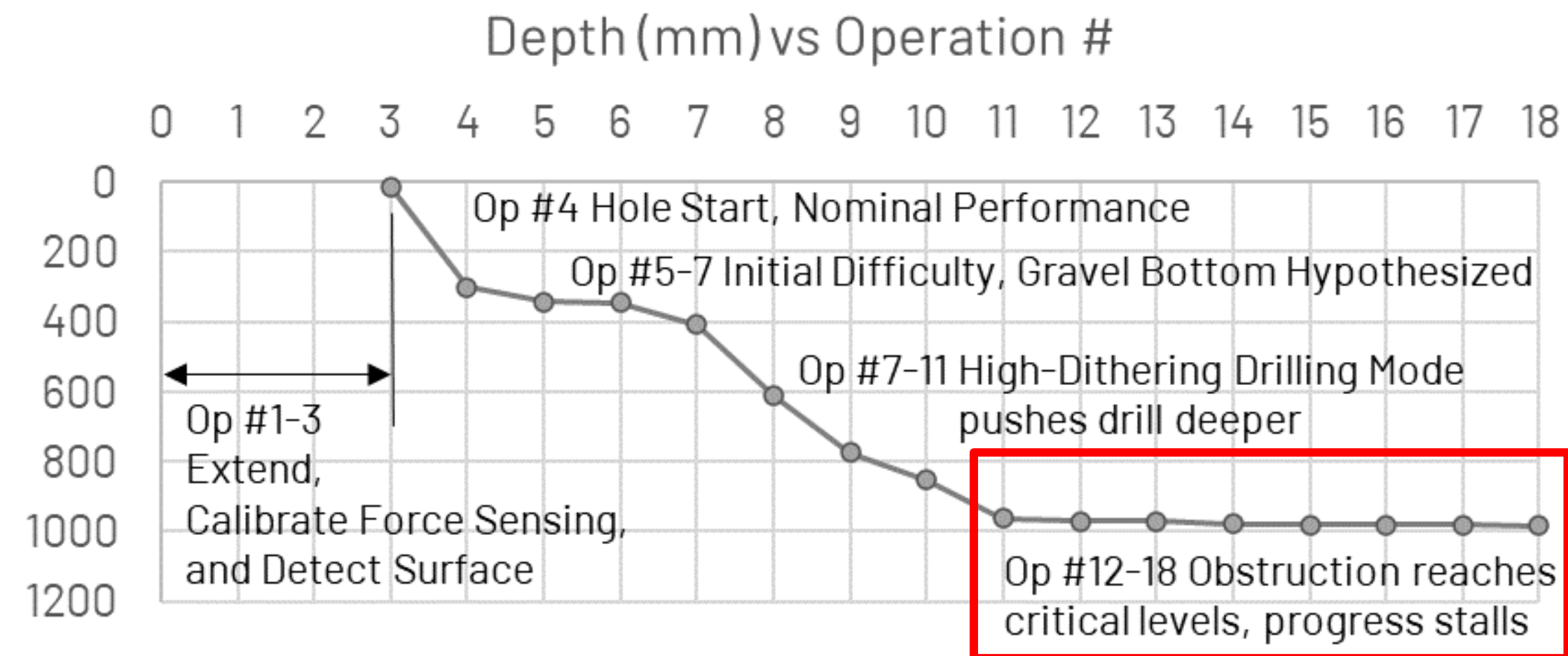


- Reduced dither retract distance vs nominal, leading to a “pecking” behavior of drill
  - Increased number of dithers in one spot prior to exit
- Prolonged “pecking” in one spot before making significant jump in progress
- Video was unable to be captured during these drilling events





# Drilling End of Life



- Eventually, enough gravel had settled at the bottom of the hole that LISTER could not progress without running into motor stalling issues, signaling end of life for drilling progression
  - Science measurements at bottom hole continued into the beginning of lunar night
- Despite realizing risks associated with limiting total drilling depth, LISTER became the first robotic measurement of lunar heat flow and the deepest-reaching robotic planetary subsurface thermal probe



Initial Ground Contact →  
0.25m depth hole →  
1.0m depth hole



# QUESTIONS?